# U.S. Army Tank-Automotive Research, Development, and Engineering Center Warren, Michigan

#### **Abstract**

1

Previous articles series in this have covered the time behavior battle force strengths, recursive and trajectories. battle relationships between parameters. In this edition, the general solution to the Markov equation is derived and effects of compared segmented battle are modes. with traditional conflict and repair Survivability, lethality. compared command as are New graphic techniques options. reveal are explored to fundamental features of this combat structure.

### INTRODUCTION

A Markov process is one in which the change between states is conservative and where the final state depends only on the initial state and a transition operator. In order to characterize this process, a 3X3 matrix representation is used to describe the operator. A state vector is also used to specify the current values of Blue, Red units (or tanks) and D (number of tanks of either side that have been damaged at that stage of the engagement). Once the operator and the initial state vector have been specified, the final or terminal state of combat can be derived.

The form for the operator and state vector product is

$$\begin{bmatrix} S_B & 0 & G_B \\ 0 & S_R & G_R \\ 1 - S_B & 1 - S_R & K \end{bmatrix} \begin{bmatrix} B \\ R \\ D \end{bmatrix}$$

Where

S<sub>B</sub> = fraction of Blue tanks surviving the previous engagement

G<sub>B</sub> = fraction of damaged tanks (both Blue and Red) put back in service on the Blue side.

$$K = 1 - G_B - G_R$$

B = current number of active
Blue Tanks

R = current number of active
Red tanks

In the material that follows the total number of tanks involved in the combat will be assumed to be 100. The state variables form a conservative system, i.e.,

$$B + R + D = 100$$

As the battle progresses between Blue and Red forces, a final eigenstate is reached that can be described by the following equations.

maintaining the data needed, and c including suggestions for reducing	lection of information is estimated to ompleting and reviewing the collect this burden, to Washington Headqu uld be aware that notwithstanding ar DMB control number.	ion of information. Send comments arters Services, Directorate for Infor	regarding this burden estimate mation Operations and Reports	or any other aspect of th , 1215 Jefferson Davis I	is collection of information, Highway, Suite 1204, Arlington		
1. REPORT DATE		2. REPORT TYPE		3. DATES COVERED			
01 APR 2001		N/A		-			
4. TITLE AND SUBTITLE				5a. CONTRACT I	NUMBER		
Survivability: A Markov Process					5b. GRANT NUMBER		
				5c. PROGRAM ELEMENT NUMBER			
6. AUTHOR(S)  Dr. Jack G. Parks				5d. PROJECT NUMBER			
				5e. TASK NUMBER			
					5f. WORK UNIT NUMBER		
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) USA TACOM 6501 E 11 Mile Road Warren, MI 48397-5000					8. PERFORMING ORGANIZATION REPORT NUMBER 16199		
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)					10. SPONSOR/MONITOR'S ACRONYM(S)  TACOM TARDEC		
					11. SPONSOR/MONITOR'S REPORT NUMBER(S)		
12. DISTRIBUTION/AVAIL Approved for publ	LABILITY STATEMENT ic release, distributi	on unlimited					
13. SUPPLEMENTARY NO	OTES						
14. ABSTRACT							
15. SUBJECT TERMS							
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF	18. NUMBER	19a. NAME OF		
a. REPORT unclassified	b. ABSTRACT <b>unclassified</b>	c. THIS PAGE <b>unclassified</b>	ABSTRACT SAR	OF PAGES  6	RESPONSIBLE PERSON		

**Report Documentation Page** 

Form Approved OMB No. 0704-0188

$$S_B B_o + G_B D_o = B_o$$
  
 $S_R R_o + G_R D_o = R_o$   
 $(1 - S_R) B_o + (1 - S_R) R_o + K D_o = D_o$ 

Solving these simultaneous equations yields the eigenstate components of the transition (or Markov) operator parameters.

$$B = 100 \left( \frac{G_B}{1 - S_B} \right) \left[ \frac{G_B}{1 - S_B} + \frac{G_R}{1 - S_R} + 1 \right]^{-1}$$

$$R = 100 \left( \frac{G_R}{1 - S_R} \right) \left[ \frac{G_B}{1 - S_B} + \frac{G_R}{1 - S_R} + 1 \right]^{-1}$$

$$D = 100 \left[ \frac{G_B}{1 - S_B} + \frac{G_R}{1 - S_R} + 1 \right]^{-1}$$

### THE GENERAL SOLUTION

Application of the Markov matrix or operator on the state vector yields the system trajectory.

$$\begin{bmatrix} S_{B} & 0 & G_{B} \\ 0 & S_{R} & G_{R} \\ 1 - S_{B} & 1 - S_{R} & K \end{bmatrix} \begin{bmatrix} B_{n} \\ R_{n} \\ D_{n} \end{bmatrix} = \begin{bmatrix} B_{n+1} \\ R_{n+1} \\ D_{n+1} \end{bmatrix}$$

**Explicitly** 

$$B_{n+1} = S_B B_n + G_B D_n$$
  
$$R_{n+1} = S_R R_n + G_R D_n$$

During the operation of the matrix operator the components of the state variable are conserved, i.e.,

$$B_n + R_n + D_n = C$$

and expression for  $B_{n+1}$  can be written as

$$B_{n+1} = S_B B_n + G_B (C - B_n - R_n)$$
  
=  $(S_B - G_B) B_n - G_B R_n + G_B C$ 

Subtracting B from both sides of the last equation yields

$$DB = B_{n+1} - B_n = (S_B - G_B - 1) - G_B R_n + G_B C$$

$$DR = (S_R - G_R - 1) R_n - G_R B_n + G_R C$$

In order to find the trajectory we need to solve the coupled differential equations

$$DX = A_x \bullet X - G_B \bullet Y + G_B C$$
$$DY = A_v \bullet Y - G_R \bullet X + G_R C$$

Where

$$X = B$$

$$Y = R$$

$$A_x = S_B - G_B - 1$$

$$A_y = S_R - G_R - 1$$

The equations involving DX and DY can be rearranged as follows

$$(D - A_x)X + G_BY = G_BC$$
  

$$(D - A_y)Y + G_RX = G_RC$$

Treating (D-A<sub>y</sub>) as an operator yields the following pair of equations

$$(D - A_y)(D - A_x)x + G(D - A_y)y = -A_yG_BC$$

$$G_BG_Rx + G_B(D - A_y)y = G_BG_RC$$

Eliminating "y" terms produces the following expression

$$[D^{2} - (A_{x} + A_{y})D + (A_{x}A_{y} - G_{x}G_{y})]x$$
$$= -G_{R}C(A_{y} - G_{R})$$

Expansion of this last equation yields

$$[D^2 - (A_x + A_y)D + (A_x A_y - G_B G_R)]x$$
  
=  $-G_B C(A_y - G_R)$ 

The general solution is as follows

$$x = C_1 e^{m_+ t} + C_2 e^{m_- t} + W$$

where

$$m_{\pm} = \frac{1}{2} \left[ \left( A_x + A_y \right) \pm \sqrt{\left( A_x - A_y \right)^2 + 4G_B G_R} \right]$$

and

$$W = -G_B C(A_y + G_R)/(A_x A_y - G_B G_R)$$

W is the final state value of x and can be written in the more familiar form

$$x_{final} = W = C \left( \frac{G_B}{1 - S_B} \right) / \left( \frac{G_B}{1 - S_B} + \frac{G_R}{1 - S_R} + 1 \right)$$

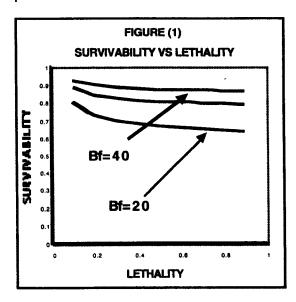
### SURVIVABILITY & LETHALITY

The question often asked is "what is more important; survivability or lethality? In order to examine this question, the equation for  $B_0$  can be rearranged to highlight  $S_B$  and  $1-S_R$ 

$$1 - S_B = \left[ \frac{10^2}{B_f} - 1 \right] \bullet \left[ \frac{1 - S_R}{1 + 10(1 - S_R)} \right]$$

In the above equation  $G_B=G_R=0.1$ .

Figure (1) displays Blue force survivability versus Blue lethality where Blue's final force value is used as a parameter



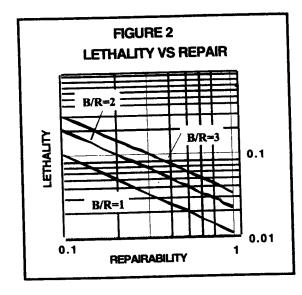
For high values of Blue survivability and significant final state values, lethality variations have little effect on the outcome of the battle. For instance, if the blue commander wants to have a final state of 40 tanks, choosing survivability values between 0.85 and 0.9 corresponds to having a lethality between 0.2 and 0.9. In other words, possessing high survivability allows considerable flexibility in using lethality values in achieving a given final combat vehicle number.

1-S <sub>R</sub>	0.9			0.1		
B <sub>f</sub>	40	30	20	40	30	20
R <sub>f</sub>	6	7	8	30	33	72

Note that when Red survivability is high, the Red Force end strength can exceed Blue end strength. Final force strenghts are equal when survivability factors are equal.

## LETHALITY & REPAIR

A second comparison involves Blue's lethality and repair. Assume that Blue's survival is 0.9 and Red's repair rate is 0.1. Figure (2) is a plot of  $1\text{-}S_R$  (i.e. Blue's lethality) versus Blue's repair rate,  $G_B$ , for different final state ratios.



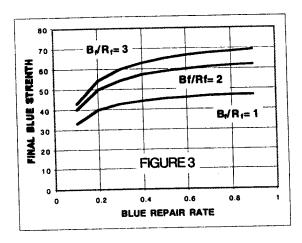
The combat equation for these results is

$$B_f / R_f = \frac{G_B (1 - S_R)}{G_R (1 - S_B)}$$

The Blue commander may wish to know if his remaining force strength will be sufficiently large. The expression

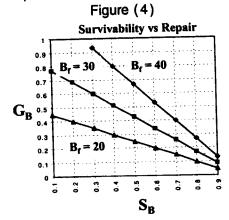
$$B_f = 100 \left( \frac{G_B}{1 - S_B} \right) \div \left( \frac{G_B}{1 - S_B} + \frac{G_R}{1 - S_R} + 1 \right)$$

can then be used to find Blue's final strength.  $B_f$  versus  $G_B$  consistent with the values of  $G_R$  and 1-S<sub>B</sub> used in Figure (2) are displayed in Figure (3).



## SURVIVABILITY & REPAIRABILITY

When Blue survival rates are compared with Blue repair rates (for constant values of  $B_f$ ), Figure (4) is the result (In this example  $S_R = 0.9$ ,  $G_R = 0.1$ , and  $B_O = 50$ ).



Lower values of  $S_B$  must be compensated by increased values of  $G_B$  in order to maintain constant  $B_f$ . For example, when  $S_B = 0.4$ ,  $G_B$  must be 0.8 in order that  $B_f$  be equal to 40.

The defining equation in this instance is

$$S_B = 1 - G_B \frac{\left[\frac{100}{B_f} - 1\right]}{\left[\frac{G_R}{1 - S_R}\right]}$$

It is useful to examine R values for the tree B values shown in Figure ().

$B_{\rm f}$	40	30	20
$R_{\rm f}$	30	35	40

The diagonal  $S_B = 1 - G_B$  in Figure divides the regions into victory and defeat regions.

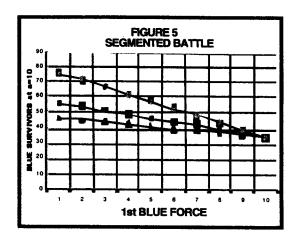
$$S_B > 1 - G_B \xrightarrow{then} B_f > R_f$$

$$S_B < 1 - G_B \xrightarrow{then} B_f < R_f$$

### SEGMENTED BATTLES

Markov type engagements are generally envisioned as combat encounters which are continuous from inception, or contact, until one side is obliterated or quits the battlefield. In real life, however, battles are frequently fought in stages ranging from skirmishes to major conflict.

Assume for the moment that the Markov engagement between Blue and Red forces only involves survivability factors of each force (which for this discussion are considered equal) and that the Blue commander first attacks a portion of the Red force until the nth stage of conflict. Starting at n+1, all the remaining Blue tanks engage all the surviving and not yet engaged Red units. Figure (5) shows the number of surviving Blue units at n=10 as a function of the number of Red targets attacked up and through the nth stage. The three curves in this figure represent various n values when full force engagement commences.



### 3D REPRESENTATIONS

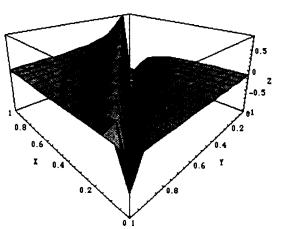


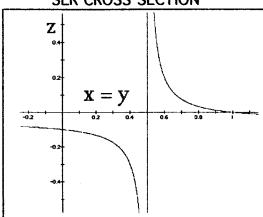
FIGURE 6: SURVIVAL, LETHALITY, REPARABILITY

In Figure (6) the behavior of the Blue force is displayed in terms of three basic battle parameters; Blue survivability (y), Blue lethality (z), and Blue reparability(x). The corresponding equation of this surface is given by the following expression:

$$1 - S_R = G_R \left[ \frac{G_B}{1 - S_B} \left( \frac{100}{B_f} - 1 \right) - 1 \right]^{-1}$$

When a plane described by the equation x=y is drawn in Figure (6), the intersection of the plane with the survival, lethality, reparability surfaces shown in Figure (7).

FIGURE 7 SLR CROSS SECTION



Lethality (Z) is always positive. addition survivability and reparability are also positive parameters. The portion of Figure (7) that is positive in Z and lies beyond x = y = 0.5 is physically allowed. A negative value of lethality, while possible to interpret as enemy captures of Blue units, was not considered in this When the repair rate for Red paper. units is 0.1 and it is recognized that z exceed value of cannot а 1.0. examination of the last equation yields a lower limit of x (or y) of 0.524.

### CONCLUSIONS

The first conclusion to be drawn from these calculations is that the Blue commander achieves superior benefit from investing in survivability compared with lethality improvements. In the example used in connection with Figure (1) changes in survivability were nearly fourteen times more effective than changes in lethality when the final Blue force strength is kept constant.

With respect to lethality and repair, consider the situation where Blue's repair rate is 0.6, final Blue force is 60 units, final Red force is 30 units, Blue Survivability is 0.9 and Red repair rate is 0.1. Then Equation () then indicates that Blue's lethality should be 0.0333. That same equation indicates that the product of repair rate and lethality should be a constant when the final states show a constant ratio. When Blue repair rate is 0.2, Figure (2) yields a Blue lethality value of 0.1 or 10 %.

Survivability and repair exhibit a linear relationship when Blue's final value is kept constant (see Figure 4)

### **BIBLIOGRAPHY**

Sharpe, Michael, General Theory of Markov Processes (Pure and Applied Mathematics, Vol. 133), 1988, Academic Press

Parks, Jack G., Survivability, Lethality, and Battlefield Repairability as Markov Processes, Proceedings of the 1999 Military, Government and Aerospace Simulation Symposium, April 1999

Parks, Jack G., Analysis and Implications of Markov Combat, Proceedings of the 1998 Military, Government and Aerospace Simulation Symposium, April 2000